

## 光学系统设计技巧(续)

郑保康

(云南北方光电仪器有限公司 昆明 650114)

### § 4.11.3 实例

1. 例1. 设计 35mm 10<sup>×</sup> 电影摄影物镜, 其具体的技术要求为:

焦距:  $f'_{25} \sim 250$ ,

相对孔径  $D/f'$ : 1/3.2 ~ 1/22,

视场: 35mm 电影摄影用胶片, 尺寸 16 × 22。

拍摄最近距离: 2.5 米

设计步骤如下:

#### (1) 确定参数和选择型式

变焦距物镜的焦距、相对孔径和视场都是根据使用单位的要求提出来而确定下来的, 本例的参数已确定。我们根据这些参数要求, 选择合适的结构型式。根据焦距 25 ~ 250mm 10<sup>×</sup> 的要求, 倍数是中等的, 相对孔径、视场都较大, 而且摄影物镜对象质要求较高, 因此我们选择机械补偿的结构型式, 因为光学补偿达到 10<sup>×</sup> 是困难的。根据国内外的设计情况, 采用国内外普遍采用的型式四组元系统, 正组补偿非物象交换原则。

#### (2) 分配焦距及间隔

取  $m_{2\text{长}} = -1.1^*$ ,  $f'_2 = -1$ ,  $f'_3 = 1.3$ ,  
 $d_{23\text{长}} = 0.5$ ,

长焦位置:

$$\begin{aligned} \because \frac{1}{l'_2} - \frac{1}{l_2} &= \frac{1}{f'_2}, \therefore m_{2\text{长}} = \frac{l'_2}{l_2}, \\ \therefore \frac{1}{m_{2\text{长}} \cdot l_2} - \frac{1}{l_2} &= \frac{1}{f'_2}, \frac{1 - m_{2\text{长}}}{m_{2\text{长}} l_2} = \frac{1}{f'_2}, \\ l_2 &= \frac{1 - m_{2\text{长}} f'_2}{m_{2\text{长}}} = \frac{1 - (-1.1)(-1)}{-1.1} (-1) \end{aligned}$$

$$= 1.909091,$$

$$l'_2 = m_{2\text{长}} l_2 = -2.1$$

$$l_3 = l'_2 - d_{23\text{长}} = -2.1 - 0.5$$

$$= -2.6 \text{ (见图 4.110 所示),}$$

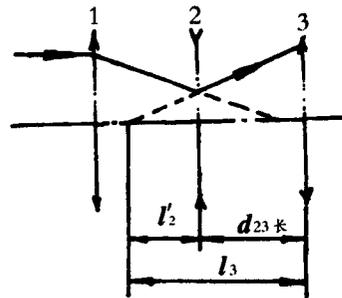


图 4.110

$$l'_3 = \frac{l_3 f'_3}{f'_3 + l_3} = \frac{(-2.6) \times 1.3}{1.3 + (-2.6)} = 2.6$$

长焦的  $m_{2\text{长}}$  取  $-1.1^*$  还是  $-1^*$ , 还是  $-1.2^*$ , 看取什么数有利于结构小, 而象差容易校正, 往大负数取接近物象交换原则, 往小负数取远离物象交换原则。

短焦位置:

$$\text{取 } m_{2\text{短}} = -0.26,$$

$$l_2 = \frac{1 - m_2 f_2'}{m_2} = \frac{1 - (-0.26)}{-0.26} \times (-1)$$

$$= 4.84615,$$

$$l_2' = m_2 l_2 = -0.26 \times 4.84615 = -1.26,$$

$$q = l_{2短} - l_{2长} = 4.84615 - 1.909091$$

$$= 2.937059 \text{ (导程)}$$

其图 4.111 所示的实线为短焦位置, 虚线为长焦位置。

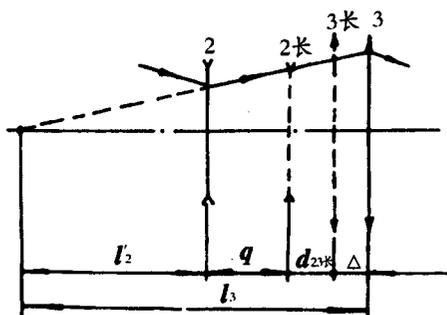


图 4.111

$$l_3 = l_2' - q - d_{23长} - \Delta$$

$$l_3 = -1.26 - 2.937059 - 0.5 - \Delta$$

$$= -4.697059 - \Delta$$

$$l_3' = l_{3长}' - \Delta = 2.6 - \Delta$$

$$\therefore \frac{1}{l_3'} - \frac{1}{l_3} = \frac{1}{f_3}$$

解上式得:

$$\frac{1}{2.6 - \Delta} + \frac{1}{4.697059 + \Delta} = \frac{1}{1.3}$$

$$4.69706 \times 2.6 - 4.69706 \Delta + 2.6 \Delta - \Delta^2$$

$$= 1.3 \times 7.29706$$

$$\Delta^2 + 2.09706 \Delta - 2.7262 = 0,$$

$$\Delta = \frac{-2.09706 \pm 3.91}{2}, \text{取绝对值小的根}$$

得到:

$$\Delta = 0.9065.$$

$$\therefore l_3 = -4.69706 - 0.9065$$

$$= -5.60356$$

$$l_3' = 2.6 - \Delta = 1.6935,$$

$$\therefore m_{2长} = -1.1, m_{3长} = \frac{l_{3长}'}{l_{3长}} = \frac{2.6}{-2.6}$$

$$= -1$$

$$m_{2短} = -0.26, m_{3短} = \frac{l_{3短}'}{l_{3短}}$$

$$= \frac{1.6935}{-5.60356} = -0.3022186,$$

$$\Gamma = \frac{m_{2长} m_{3长}}{m_{2短} m_{3短}}$$

$$= \frac{(-1.1) \times (-1)}{(-0.26) \times (-0.3022186)}$$

$$= 13.999^{\times},$$

得到的计算结果倍率太大, 我们要求是  $10^{\times}$ , 所以要重新取  $m_{2短}$ , 直到总倍率  $\Gamma$  接近  $10^{\times}$ , 而略大于  $10^{\times}$ 。

重新计算短焦位置:

我们取  $m_{2短} = -0.3$ , 进行计算, 具体计算略, 只列出计算结果:

$$l_2 = \frac{1.3}{0.3} = 4.3333,$$

$$l_2' = -1.3$$

$$q = 4.3333 - 1.9091 = 2.4242,$$

$$l_3 = -5.0767,$$

$$l_3' = 1.7475,$$

$$m_{2长} = -1.1, m_{2短} = -0.3,$$

$$m_{3长} = -1, m_{3短} = \frac{1.7475}{-5.0767} = -0.344,$$

$$\text{得到 } \Gamma = \frac{m_{2长} m_{3长}}{m_{2短} m_{3短}} = 10.65^{\times}.$$

基本符合要求  $10^{\times}$ , 略大于  $10^{\times}$  是合理的, 因为理想系统变为实际系统往往由于间隔不够而使实际倍率降低, 一般比实际要求倍率大  $0.5^{\times}$  左右是合适的。

求各组焦距:

取  $d_{34短} = 0.4$  (主要考虑 3 与 4 透镜组在短焦不相碰)

取  $d_{12短} = 0$  (主要考虑1与2透镜组在短焦位置不相碰), 我们准备用复杂的前固定组, 使主面往后移来实现  $d_{12短} = 0$ 。

$$f'_1 = l_{2短} + d_{12短} = 4.3333 + 0 = 4.3333,$$

$$f'_2 = -1 \text{ (前面取定的)}$$

$$f'_3 = 1.3 \text{ (前面取定的)}$$

我们取  $f'_1 = 170$  (或不取  $f'_1$ , 而由系统的总焦距〈长焦或短焦〉及取  $m_4$  值而求  $f'_1$ , 即按式  $F_{1234短} = f'_1 m_{2短} \cdot m_{3短} \cdot m_4$ , 求出)。

$$f'_2 = \frac{170}{4.3333} \times (-1) = -39.23,$$

$$f'_3 = \frac{170}{4.3333} \times 1.3 = 51,$$

$$\because F_{1234短} = f'_1 m_{2短} \cdot m_{3短} \cdot m_4 = F_{1234长} / \Gamma$$

$F_{1234长} = f'_1 m_{2长} \cdot m_{3长} \cdot m_4 = 250$  ( $\because$  我们要求长焦总焦距为 250mm)

$$m_4 = \frac{250}{f'_1 m_{2长} \cdot m_{3长}} = \frac{250}{170 \times (-1.1) \times (-1)} = \frac{250}{187} = 1.3369$$

$$\because l_4 = l'_{3短} - d_{34短} = 1.7475 - 0.4 = 1.3475$$

$$l'_4 = m_4 l_4 = 1.3475 \times 1.3369 = 1.80147,$$

$$f_4 = \frac{l'_4 l_4}{l_4 - l'_4} = \frac{1.80147 \times 1.3475}{1.3475 - 1.80147} = -5.34723,$$

$$F_{1234短} = \frac{250}{10.65} = 23.474,$$

$$f'_{1234长} = 4.3333 \times (-1.1) \times (-1) \times 1.3369 = 6.3725,$$

$$f'_{1234短} = \frac{6.3725}{10.65} = 0.5983568$$

$$M = \frac{250}{6.3725} = 39.23107 \text{ (缩放比)}$$

我们将上面的计算结果归纳如下:

$$f'_1 = 4.3333 \quad f'_1 = 170$$

$$f'_2 = -1 \xrightarrow{\text{缩放成实际值}} f'_2 = -39.23$$

$$f'_3 = 1.3 \quad f'_3 = 51,$$

$$f'_4 = -5.34723 \quad f'_4 = -209.777$$

$$\Delta = 0.8525 \quad \Delta = 33.444$$

$$q = 2.4242 \quad q = 95.104$$

$$\text{总长} = q + \Delta + d_{3短} + l'_4 + d_{2长} \quad \text{总长} = 234.53$$

$$= 5.97817$$

短焦:

$$d_{12} = 0 \quad d_{12} = 0$$

$$d_{23} = q + \Delta + d_{23长} \quad d_{23} = 148.164$$

$$= 3.7767$$

$$d_{34} = 0.4 \quad d_{34} = 15.692$$

$$l'_4 = 1.80147 \quad l'_4 = 70.6736$$

$$F_{1234短} = 23.474$$

长焦:

$$d_{12} = q = 2.4242 \quad d_{12} = 95.104$$

$$d_{23} = 0.5 \quad d_{23} = 19.616$$

$$d_{34} = 0.4 + \Delta = 1.2525 \quad d_{34} = 49.137$$

$$l'_4 = 1.80147 \quad l'_4 = 70.6736$$

$$F_{1234长} = 250$$

(3) 求长、短焦的  $h, h_p$

短焦位置:

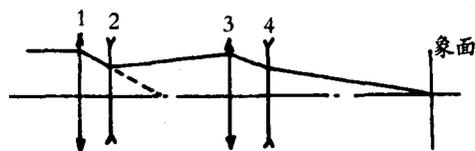


图 4.112

如图 4.112 所示是四组元的非物象交换原则的正组补偿系统。

求  $h$ :

$$\begin{aligned} \therefore h_1 &= \frac{F_{1234\text{短}}}{2A} = \frac{23.474}{6.4} \\ h_1 &= 3.6678, \\ u_1 &= 0 \\ \Delta u_1 &= u_2 - u_1 = h_1 \varphi_1 = 3.6678/170 \\ &= 0.02157529, \\ \therefore u_2 &= h_1 \varphi_1 + u_1 = 0.02157529, \\ \therefore h_2 &= h_1 - d_{12} u_2 = 3.6678 - 0 \times \\ &0.02157529 = 3.6678, \\ \Delta u_2 &= u_3 - u_2 = h_2 \varphi_2 = 3.6678 \div \\ &(-39.23) = -0.0934948, \\ \therefore u_3 &= h_2 \varphi_2 + u_2 = -0.0934948 \\ &+ 0.02157529 = -0.0719195 \\ \therefore h_3 &= h_2 - d_{23} u_3 = 3.6678 - 148.164 \\ &\times (-0.0719195) = 14.3237, \\ \Delta u_3 &= u_4 - u_3 = h_3 \varphi_3 = 14.3237/51 \\ &= 0.280857, \\ \therefore u_4 &= h_3 \varphi_3 + u_3 = 0.2089375, \\ \therefore h_4 &= h_3 - d_{34} u_4 = 14.3237 - 15.692 \\ &\times 0.2089375 = 11.0451, \\ \Delta u_4 &= u'_4 - u_4 = h_4 \varphi_4 = 11.0451 \div \\ &(-209.777) = -0.0526516, \\ \therefore u'_4 &= h_4 \varphi_4 + u_4 = -0.0526516 \\ &+ 0.2089375 = 0.1562859, \\ \text{校对: } h_1/u'_4 &= 3.6678/0.1562859 = \\ &23.468 (\text{与 } F_{1234\text{短}} = 23.474 \text{ 基本相符}) \end{aligned}$$

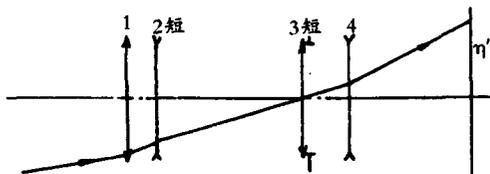


图 4.113

求  $h_p$  :

已知:

$$f'_1 = 170,$$

$$\begin{aligned} f'_2 &= -39.23, \\ f'_3 &= 51, \\ f'_4 &= -209.777, d_{12} = 0, \\ d_{23} &= 148.164, d_{34} = 15.692, \\ l'_4 &= 70.6736, F_{1234\text{短}} = 23.474 \end{aligned}$$

我们先假定在补偿组 3 处在短焦位置处放置光栏, 根据  $\eta'$  求出  $h_{p4}$ 。从图 4.114 中我们可以得出如下关系式:

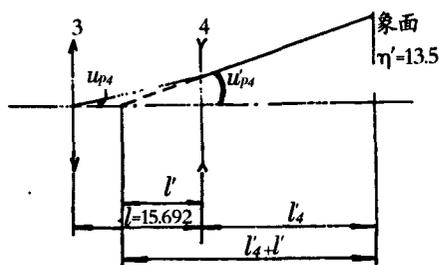


图 4.114

$$\begin{aligned} \therefore \frac{1}{l'} - \frac{1}{l} &= \frac{1}{f'} \\ l' &= \frac{l f'}{l + f'} = \frac{-15.692 \times (-209.777)}{-15.692 + (-209.777)} \\ l' &= -14.5998 \\ \therefore \frac{h_{p4}}{\eta'} &= \frac{l'}{l' + l'_4} \\ h_{p4} &= \frac{14.5998 \times 13.5}{14.5998 + 70.6736} \\ &= 2.311357, \\ \therefore u'_{p4} &= \frac{\eta'}{l' + l'_4} = \frac{13.5}{85.2734} \\ &= 0.1583143, \\ \therefore u_{p4} &= \frac{h_{p4}}{d_{34}} = \frac{2.311357}{15.692} \\ &= 0.14729525, \\ \therefore h_{p3} &= 0 \\ \therefore \Delta u_{p3} &= u_{p4} - u_{p3} = h_{p3} \varphi_3, \\ \therefore u_{p4} - u_{p3} &= 0, \\ \therefore u_{p3} &= u_{p4} = 0.14729525, \end{aligned}$$

$$\begin{aligned} \because h_{p2} &= u_{p3}d_{23} = 0.14729525 \times \\ 148.164 &= 21.82385, \\ \because \Delta u_{p2} &= u_{p3} - u_{p2} = h_{p2}\varphi_2 \\ &= 21.82385 / (-39.23) = -0.556305, \\ \therefore u_{p2} &= 0.14729525 + 0.556305 \\ &= 0.7036, \\ \because h_{p1} &= h_{p2} + u_{p2}d_{12} = h_{p2} \\ &= 21.82385, \\ \because \Delta u_{p1} &= u_{p2} - u_{p1} = h_{p1}\varphi_1 \\ &= 21.82385 / 170 = 0.1283756, \\ \therefore u_{p1} &= 0.7036 - 0.1283756 \\ &= 0.5752244. \end{aligned}$$

校对:  $\eta' = u_{p1}F_{1234\text{短}} = 23.474 \times 0.5752244 = 13.5028$  (与  $\eta' = 13.5$  基本相符)

长焦位置:

同样方法求长焦位置的  $h, h_p$ , 这里我们不具体计算, 只是在后面结果中列出计算结果。

#### (4) 中间插点

根据计算得到的长短焦位置的  $h, h_p$ , 看一下  $h, h_p$  是否太大, 若外形尺寸可以, 就继续计算中间几个点子, 一般讲中间插上三个点子即可以, 我们准备插上:

$$m_2 = \begin{cases} -0.79 (\text{次长}) \\ -0.57 (\text{中焦}) \\ -0.413 (\text{次短}) \end{cases}$$

计算中焦位置:

焦距、间隔计算:

$$\begin{aligned} m_2 &= -0.57 \\ l_2 &= \frac{1 - m_2 f_2}{m_2} = \frac{1 - (-0.57)}{-0.57} (-1) \\ &= \frac{1.57}{0.57} = 2.754386, \end{aligned}$$

$$\begin{aligned} l_2' &= m_2 l_2 = (-0.57) \times 2.754386 \\ &= -1.57, \\ q &= l_{2\text{短}} - l_2 = 4.3333 - 2.754386 \\ &= 1.578914, \\ \because l_3 &= l_2' - d_{23}, d_{23} = d_{23\text{短}} - q_1 - \Delta_1, \\ \therefore l_3 &= l_2' - d_{23\text{短}} + q_1 + \Delta_1 \\ &= -1.57 - 3.7767 + 1.578914 + \Delta_1 \\ &= -3.767786 + \Delta_1 \\ l_3' &= l_{3\text{短}} + \Delta_1 = 1.7475 + \Delta_1 \\ \frac{1}{l_3'} - \frac{1}{l_3} &= \frac{1}{f_3} = \frac{1}{1.3}, \text{将上面两式代入} \end{aligned}$$

此式得:

$$\begin{aligned} \frac{1}{1.7475 + \Delta_1} - \frac{1}{-3.7678 + \Delta_1} &= \frac{1}{1.3} \\ \Delta_1^2 - 2.0203 \Delta_1 + 0.5857 &= 0, \\ \Delta_1 &= \frac{2.0203 \pm 1.319}{2} \end{aligned}$$

$\Delta_1 = 0.35065$  (另一根不合, 因为  $\Delta_1$  总是小于  $\Delta$ )

$$\begin{aligned} \therefore l_3 &= -3.767786 + 0.35065 \\ &= -3.417136, \\ l_3' &= 1.7475 + 0.35065 = 2.09815, \\ m_3 &= \frac{l_3'}{l_3} = \frac{2.09815}{-3.417136} = -0.614, \\ d_{12} &= f_1' - l_2 = 4.3333 - 2.754386 \\ &= 1.5789 \\ d_{23} &= d_{23\text{短}} - q_1 - \Delta_1 = 3.7767 - \\ &1.578914 - 0.35065 = 1.847136, \\ F_{1234\text{中}} &= f_1' m_{2\text{中}} \cdot m_{3\text{中}} \cdot m_4 = 4.3333 (- \\ &0.57) (-0.614) (1.3369) = 2.0275, \end{aligned}$$

归纳如下: 实际值

$$\begin{aligned} l_3 &= -3.417136, & l_3 &= 134.058, \\ l_3' &= 2.09815, & l_3' &= 82.313, \\ \Delta_1 &= 0.35065, & \Delta_1 &= 13.756, \\ d_{12} &= 1.5789, & d_{12} &= 61.942, \end{aligned}$$



$$\begin{cases} u_1 = 0 \\ u_2 = 0.0216 \\ u_3 = -0.072 \\ u_4 = 0.2088 \end{cases} \quad \begin{cases} |u_1 = 0 \\ |u_2 = -0.230682 \\ |u_3 = -0.25639 \\ |u_4 = -3.98169 \end{cases}$$

次短:

$$\begin{cases} h_1 = 6.719 \\ h_2 = 5.325 \\ h_3 = 15.577 \\ h_4 = 11.04 \end{cases} \quad \begin{cases} h_{p1} = 32.502 \\ h_{p2} = 14.718 \\ h_{p3} = 0.909 \\ h_{p4} = -2.31 \end{cases}$$

$$\begin{cases} u_1 = 0 \\ u_2 = 0.0395 \\ u_3 = -0.096 \\ u_4 = 0.2088 \end{cases} \quad \begin{cases} |u_1 = 0 \\ |u_2 = -0.29152 \\ |u_3 = -0.31493 \\ |u_4 = -3.98169 \end{cases}$$

中焦:

$$\begin{cases} h_1 = 12.4283 \\ h_2 = 7.9 \\ h_3 = 17.195 \\ h_4 = 11.043 \end{cases} \quad \begin{cases} h_{p1} = 31.984 \\ h_{p2} = 9.8209 \\ h_{p3} = 2.0262 \\ h_{p4} = -2.31 \end{cases}$$

$$\begin{cases} u_1 = 0 \\ u_2 = 0.0731 \\ u_3 = -0.1282 \\ u_4 = 0.2088 \end{cases} \quad \begin{cases} |u_1 = 0 \\ |u_2 = -0.36365 \\ |u_3 = -0.38099 \\ |u_4 = -3.98169 \end{cases}$$

次长:

$$\begin{cases} h_1 = 23.1 \\ h_2 = 12.1 \\ h_3 = 19.42 \\ h_4 = 11.04 \end{cases} \quad \begin{cases} h_{p1} = 27.18 \\ h_{p2} = 6.86 \\ h_{p3} = 3.62 \\ h_{p4} = -2.31 \end{cases}$$

$$\begin{cases} u_1 = 0 \\ u_2 = 0.136 \\ u_3 = -0.172 \\ u_4 = 0.2088 \end{cases} \quad \begin{cases} |u_1 = 0 \\ |u_2 = -0.44173 \\ |u_3 = -0.4525 \\ |u_4 = -3.98169 \end{cases}$$

长焦:

$$\begin{cases} h_1 = 39.1 \\ h_2 = 17.23 \\ h_3 = 21.325 \\ h_4 = 11.04 \end{cases} \quad \begin{cases} h_{p1} = 25.093 \\ h_{p2} = 5.913 \\ h_{p3} = 4.913 \\ h_{p4} = -2.31 \end{cases}$$

$$\begin{cases} u_1 = 0 \\ u_2 = 0.23 \\ u_3 = -0.2084 \\ u_4 = 0.2088 \end{cases} \quad \begin{cases} |u_1 = 0 \\ |u_2 = -0.52463 \\ |u_3 = -0.49939 \\ |u_4 = -3.98169 \end{cases}$$

$$|u_i = \frac{u_i}{h_i \varphi_i}$$

根据象差系数  $S_1 \sim S_V$  与  $IP$ 、 $IW$  的关系我们专门编一个程序,在电子计算机上进行计算,从而确定每一透镜组的  $IP$ 、 $IW$ 。程序输入的数据为:

$$\textcircled{1} J = n'u'\eta' = 1 \times 0.156244 \times (-13.5) = -2.109294,$$

$$\textcircled{2} \mu = 0.6,$$

$$\textcircled{3} B = 0.84,$$

$$\textcircled{4} c = 0.14,$$

$\textcircled{5} M = 5$  (要求 5 个位置即长、次长、中焦、次短、短焦等校正象差),

$\textcircled{6} K = 4$  (透镜组数,即前固定组、变倍组、补偿组、后固定组),

$\textcircled{7} \varphi(1 \sim K \text{ 即 } 1 \sim 4, \text{ 也就是前固定组、变倍组、补偿组、后固定组各组的光焦度}) = 0.005882; -0.025445; 0.019569; -0.004750,$

$\textcircled{8} h$  (共 20 个,即短焦 4 个、次短 4 个、中焦 4 个、次长 4 个、长焦 4 个),

$\textcircled{9} h_p$  (共 20 个即与  $\textcircled{8}$  相同),

$\textcircled{10}$  规化  $lu$  (共 20 个即与  $\textcircled{8}$  相同),

$\textcircled{11}$  校正象差的权(4 个 1,即有  $S_1 \sim S_V$  四种象差的权填 1)

$\textcircled{12} S_i$  目标值( $S_I$  5 个,  $S_{II}$  5 个,  $S_{III}$  5 个,

$S_V$  5 个) 共填 20 个零。

⑬  $IP$ 、 $IW$  的权(4 个  $IP$  的权, 4 个  $IW$  的权) 共填 8 个零。

根据计算得出的各透镜组的  $IP$ 、 $IW$ , 接下去进行  $IP$ 、 $IW$  分配; 选玻璃求半径等等, 这里不详述, 因为前面已经讲清楚了。

2. 例 2. 设计 35mm 电影摄影用的  $3\times$  变焦距物镜, 其具体技术指标为:

焦距: 25 ~ 75mm,

相对孔径  $D/f'$ : 1/2.8 ~ 1/22,

视场  $2\omega$ :  $57^\circ \sim 19.3^\circ$  (即底片尺寸 16 × 22)

最近距离: 1.5 米。

### (1) 确定参数和选择型式

本例的参数已确定(指焦距、倍率、相对孔径、视场等), 接下来是选择型式, 选用三组元机械补偿, 用 2、3 两组元运动来达到变焦目的, 用前组 1 来调焦(是整组还是部分调焦根据具体情况而定), 把光阑放于后组 3 上, 在变焦过程中光阑作相应的小量变化, 以保证孔径之不变, 第 2 组元为变倍组作线性运动, 第 3 组元为补偿组作非线性运动。关于倍率的选段问题, 我们取正组补偿物象交换原则。

### (2) 分配焦距及间隔

取  $f'_2 = -1$ ,  $f'_3 = 1.08$ ,

因为是 3 倍, 且根据正组补偿物象交换原则,

$$\therefore m_{2短} = -\frac{1}{\sqrt{3}} = -0.5774,$$

$$m_{2长} = -\sqrt{3} = -1.732,$$

长焦位置:

$$l_2 = \frac{1 - m_2 f'_2}{m_2} = \frac{1 + 1.732}{-1.732} (-1) \\ = \frac{2.732}{1.732} = 1.57736721$$

$$l'_2 = m_2 l_2 = -1.732 \times 1.57736721 \\ = -2.732,$$

取  $d_{23长} = 0.738$ ,

$$l_3 = l'_2 - d_{23长} = -2.732 - 0.738 \\ = -3.470,$$

$$l'_3 = \frac{l_3 f'_3}{l_3 + f'_3} = \frac{(-3.47) \times 1.08}{-3.47 + 1.08} \\ = 1.56803347,$$

$$m_{3长} = \frac{l'_3}{l_3} = \frac{1.56803347}{-3.470} \\ = -0.45188284,$$

$$m_{2长} \cdot m_{3长} = (-1.732) \times \\ (-0.45188284) = 0.78266108$$

短焦位置:

$$m_{2短} = -0.5774,$$

$$l_2 = \frac{1 - m_2 f'_2}{m_2} = \frac{1 + 0.5774}{-0.5774} (-1) \\ = 2.73190162,$$

$$l'_2 = m_2 l_2 = (-0.5774) \times 2.73190162 \\ = -1.5774,$$

$$q = l_{2短} - l_{2长} = 2.73190162 - \\ 1.577367205 = 1.154534415,$$

$$l_3 = l'_2 - q - \Delta - d_{23长} = -1.5774 - \\ 1.154534415 - 0.738 - \Delta,$$

$$l_3 = -3.469937715 - \Delta,$$

$$l'_3 = l_{3长} - \Delta = 1.56803347 - \Delta,$$

$$\frac{1}{l'_3} - \frac{1}{l_3} = \frac{1}{f'_3}$$

将  $l_3$  和  $l'_3$  代入上式得:

$$\Delta = \frac{-1.901900945 \pm 1.90186727}{2},$$

取较小值得:

$$\begin{aligned}\Delta &= -0.000016838, \\ l_3 &= -3.469934415 + 0.000016838 \\ &= -3.46991758, \\ l'_3 &= 1.56803347 + 0.000016838 \\ &= 1.56805031,\end{aligned}$$

$$\begin{aligned}m_{3短} &= \frac{l'_3}{l_3} = \frac{1.56805031}{-3.46991758} \\ &= -0.45189843,\end{aligned}$$

$$\begin{aligned}m_{2短} \cdot m_{3短} &= (-0.5774) \times \\ &(-0.45189843) = 0.26092615,\end{aligned}$$

$$\begin{aligned}\Gamma &= \frac{m_{2长} \cdot m_{3长}}{m_{2短} \cdot m_{3短}} = \frac{0.78266108}{0.26092615} \\ &= 2.99955 \approx 3^* \text{ (说明计算无误),}\end{aligned}$$

$$\begin{aligned}\text{取 } d_{12短} &= 0.3, \\ \therefore f'_1 &= l_{2短} + d_{12短} = 2.73190162 \\ &+ 0.3 = 3.03190162,\end{aligned}$$

$$\begin{aligned}f_{短} &= f'_1 m_{2短} \cdot m_{3短} = 3.03190162 \times \\ &0.26092615 = 0.791102417,\end{aligned}$$

$$\begin{aligned}f'_{长} &= f'_1 m_{2长} \cdot m_{3长} = 3.03190162 \times \\ &0.78266108 = 2.372951396,\end{aligned}$$

$$\text{取 } F'_{短} = 25 \text{ (实例要求的短焦距值)}$$

$$\begin{aligned}M &= \frac{F'_{短}}{f_{短}} = \frac{25}{0.791102417} \\ &= 31.6014708 \text{ (缩放比)}\end{aligned}$$

计算总长:

$$\begin{aligned}L &= (d_{12短} + d_{23长} + q + \Delta + l'_{3短})M \\ &= (0.3 + 0.738 + 1.154534415 - \\ &0.000016838 + 1.56805031) \times 31.6014708 \\ &= 118.84\end{aligned}$$

实际情况要考虑两主面的间距,估计还要略长一些。

将焦距归纳如下:

$$\begin{aligned}f'_1 &= 3.03190162 \xrightarrow{\times M} \text{实际值: } f'_1 = 95.81255051 \\ f'_2 &= -1 & f'_2 &= -31.6014708 \\ f'_3 &= 1.08 & f'_3 &= 34.12958846\end{aligned}$$

归纳长、短焦各数据:

长焦:

$$l_3 = -3.47 \xrightarrow{\times M} \text{实际值: } l_3 = -109.65710368$$

$$l'_3 = 1.56803347 \quad l'_3 = 49.55216392$$

$$\Delta = 0.000016838 \quad \Delta = 0.00053211$$

$$d_{12} = 1.454534415 \quad d_{12} = 45.96542684$$

$$d_{23} = 0.738 \quad d_{23} = 23.32188545$$

$$f'_{长} = 2.372951396 \quad f'_{长} = 74.98875425$$

$$q = 1.154534415 \quad q = 36.48498560$$

短焦:

$$l_3 = -3.46991758 \xrightarrow{\times M} \text{实际值: } l_3 = -109.65449908$$

$$l'_3 = 1.56805031 \quad l'_3 = 49.55269608$$

$$\Delta = 0 \quad \Delta = 0$$

$$d_{12} = 0.3 \quad d_{12} = 9.48044124$$

$$\begin{aligned}d_{23} &= d_{23长} + q + \Delta \quad d_{23} = 59.80633904 \\ &= 1.889251758\end{aligned}$$

$$f'_{短} = 0.791102417 \quad f'_{短} = 25$$

$$q = 0 \quad q = 0$$

中间插点:

我们准备中间插三个点,即为:

$$m_2 = \begin{cases} -1.3 \text{ (次长焦)} \\ -1 \text{ (中焦)} \\ -0.75 \text{ (次短焦)} \end{cases}$$

次长位置:

$$m_2 = -1.3$$

$$l_2 = \frac{1 - m_2 f'_1}{m_2} = \frac{1 - (-1.3)}{-1.3} (-1)$$

$$= 1.76923077,$$

$$l'_2 = m_2 l_2 = -1.3 \times 1.76923077$$

$$= -2.3$$

$$q_1 = l_{2短} - l_2 = 2.73190162 -$$

$$1.76923077 = 0.96267085,$$

如图 4.116 所示可得  $l_3$ :

$$l_3 = l'_2 - d_{23} = l'_2 - (d_{23短} - q_1 - \Delta_1)$$

$$= -2.3 - (1.89251758 - 0.96267085 - \Delta_1)$$

$$l_3 = -3.22984673 + \Delta_1$$

$$l'_3 = l'_{3短} + \Delta_1,$$

又  $\because \frac{1}{l'_3} - \frac{1}{l_3} = \frac{1}{f_3} = \frac{1}{1.08}$ , 将  $l_3$  和  $l'_3$  代入上式得:

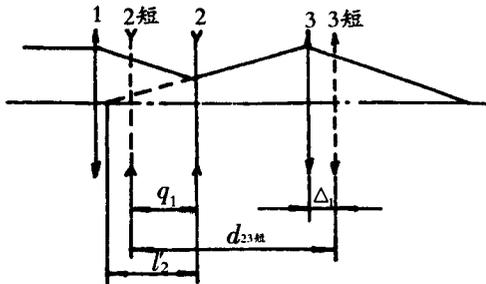


图 4.116

$$\Delta_1 = \frac{1.66179642 \pm 1.51423}{2}, \text{取较小值得:}$$

小值得:

$$\Delta_1 = 0.07378321,$$

$$l_3 = -3.15606352,$$

$$l'_3 = 1.64183352,$$

$$m_3 = \frac{l'_3}{l_3} = -0.52021561,$$

$$m_2 m_3 = (-1.3) \times (-0.52021561)$$

$$= 0.67628029,$$

$$d_{12} = f'_1 - l_2 = 3.03190162$$

$$- 1.76923077 = 1.26267085,$$

$$d_{23} = d_{23短} - q_1 - \Delta_1 = 1.89251758 -$$

$$0.96267085 - 0.07378321,$$

$$d_{23} = 0.85606352,$$

$$f'_{次长} = f'_1 m_2 m_3 = 3.03190162 \times$$

$$0.67628029 = 2.05041531,$$

$$F'_{次长} = f'_{次长} \times M = 64.79613955,$$

将数据归纳如下:

$$l_3 = -3.15606352 \xrightarrow{\times M} \text{实际值: } l_3 = -99.73624917$$

$$l'_3 = 1.64183352 \quad l'_3 = 51.88435404$$

$$\Delta_1 = 0.07378321 \quad \Delta_1 = 2.33165796$$

$$d_{12} = 1.26267085 \quad d_{12} = 39.90225599$$

$$d_{23} = 0.85606352 \quad d_{23} = 27.05286633$$

$$f'_{次长} = 2.05041531 \quad F'_{次长} = 64.79613955$$

$$q_1 = 0.96267085 \quad q_1 = 30.42181476$$

用同样的方法求出中焦、次短两位置

的数据,现将数据列于下:

中焦位置 ( $m = -1$ ):

$$l_3 = -3.05939543 \xrightarrow{\times M} \text{实际值: } l_3 = -96.68139535$$

$$l'_3 = 1.66927084 \quad l'_3 = 52.75141371$$

$$\Delta_1 = 0.10122053 \quad \Delta_1 = 3.19871762$$

$$d_{12} = 1.03190162 \quad d_{12} = 32.60960891$$

$$d_{23} = 1.05939543 \quad d_{23} = 33.47845375$$

$$f'_{中焦} = 1.65426963 \quad f'_{中焦} = 52.27735341$$

$$q_1 = 0.73190162 \quad q_1 = 23.12916767$$

次短位置 ( $m_2 = -0.75$ ):

$$l_3 = -3.17533423 \xrightarrow{\times M} \text{实际值: } l_3 = -100.34523195$$

$$l'_3 = 1.63666537 \quad l'_3 = 51.72103290$$

$$\Delta_1 = 0.06861506 \quad \Delta_1 = 2.16833682$$

$$d_{12} = 0.69856829 \quad d_{12} = 22.07578542$$

$$d_{23} = 1.42533423 \quad d_{23} = 45.04265805$$

$$f'_{次短} = 1.17205182 \quad f'_{次短} = 37.038561366$$

$$q_1 = 0.39856829 \quad q_1 = 12.59534418$$

(3) 计算  $h$  和  $h_p$

A、计算  $h$

长焦位置:

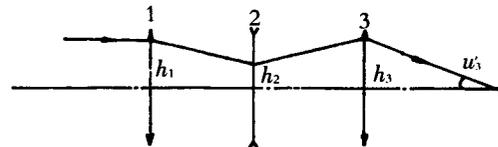


图 4.117

$$h_1 = \frac{F'_k}{2A} = \frac{74.98875425}{2 \times 2.8} = 13.39084897,$$

$$u_1 = 0$$

$$\Delta u_1 = u_2 - u_1 = h_1 \varphi_1 = \frac{13.39084897}{95.81255051}$$

$$= 0.13976091,$$

$$u_2 = 0.13976091,$$

$$h_2 = h_1 - d_{12} u_2 = 13.39084897 -$$

$$45.96542684 \times 0.13976091,$$

$$h_2 = 6.96667909,$$

$$\Delta u_2 = u_3 - u_2 = h_2 \varphi_2$$

$$= 6.96667909 / (-31.6014708)$$

$$= -0.2204542,$$

$$u_3 = -0.22045427 + 0.13976091$$

$$= -0.08069336,$$

$$h_3 = h_2 - d_{23} u_3 = 6.96667909 +$$

$$23.32188545 \times 0.08069336,$$

$$h_3 = 8.84860039,$$

$$\Delta u_3 = u'_3 - u_3 = h_3 \varphi_3$$

$$= 8.84860039 / 34.12958846$$

$$= 0.25926478,$$

$$u'_3 = 0.25926478 - 0.08069336$$

$$= 0.17857142,$$

校对： $h_1/u'_3 = 74.9887578$  (与  $F'_k = 74.98875425$  相符。) 用同样的方法求出次长、中焦、次短、短焦的  $h$  值。

B、计算  $h_p$

长焦位置：

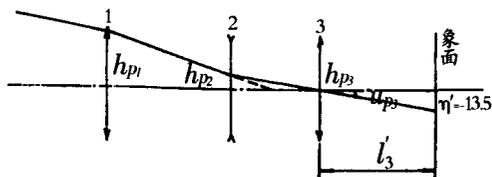


图 4. 118

我们设光阑放置于第 3 透镜组上, 所

以  $h_{p3} = 0,$

$$u'_{p3} = \frac{\eta'}{l'_3} = \frac{13.5}{49.55216392}$$

$$= 0.27244017,$$

$$u_{p3} = u'_{p3} = 0.27244017,$$

$$h_{p2} = d_{23} u_{p3} = 23.32188545 \times$$

$$0.27244017 = 6.35381844,$$

$$\Delta u_{p2} = u_{p3} - u_{p2} = h_{p2} \varphi_2$$

$$= 6.35381844 / (-31.6014708)$$

$$= -0.20106085,$$

$$u_{p2} = 0.27244017 - (-0.20106085)$$

$$= 0.47350102,$$

$$h_{p1} = h_{p2} + u_{p2} d_{12} = 6.35381844 +$$

$$0.47350102 \times 45.96542684,$$

$$h_{p1} = 28.11849493,$$

$$\Delta u_{p1} = u_{p2} - u_{p1} = h_{p1} \varphi_1 =$$

$$28.11849493 / 95.81255051 = 0.29347403,$$

$$u_{p1} = 0.47350102 - 0.29347403$$

$$= 0.18002699,$$

校对： $\eta' = u_{p1} F'_k = 13.49999971$  (与  $\eta' = 13.5$  相符。)

用同样的方法可以计算出次长、中焦、次短、短焦的  $h_p$  值。

(4) 计算规化  $lu$

根据上面计算得到的各透镜组的  $u$  值, 按如下公式进行规化:

$$lu_i = \frac{u_i}{h_i \varphi_i},$$

具体的数据在后面列出。

(5) 计算  $\varphi_i$  值

$$\varphi_1 = \frac{1}{95.81255051} = 0.010437046,$$

$$\varphi_2 = \frac{1}{-31.6014708}$$

$$= -0.031644097,$$

$$\varphi_3 = \frac{1}{34.12958846} = 0.02930009,$$

(6) 计算  $J$

$$J = n'u'\eta' = 1 \times 0.17857143 \times$$

$$(-13.5) = -2.41071431,$$

到此,上机计算  $IP$ 、 $IW$  的数据已经准备完,现将上机计算的初始数据列于下(按上机程序要求的次序):

①  $J = -2.41071431$

②  $\mu = 0.6$

③  $B = 0.84$

④  $c = 0.14$

⑤  $M = 5$  (五个焦距位置校正象差)

⑥  $K = 3$  (三个透镜组参加校正象差)

⑦  $\varphi$ :  $\varphi_1 = 0.010437046$ ;

$\varphi_2 = -0.031644097$ ;  $\varphi_3 = 0.02930009$

⑧  $h$  (长焦、次长、中焦、次短、短焦共五个焦距位置,15个  $h$  值。列于下表。)

⑨  $h_p$  (长焦、次长、中焦、次短、短焦共五个焦距位置,15个  $h$  值。列于下表。)

⑩  $lu$  (长焦、次长、中焦、次短、短焦共五个焦距位置,15个  $lu$  值。列于下表。)

	⑧ $h$	⑨ $h_p$	⑩ $lu$
长焦	$\begin{cases} h_1 = 13.39084897 \\ h_2 = 6.96667909 \\ h_3 = 8.84860039 \end{cases}$	$\begin{cases} h_{p1} = 28.11849493 \\ h_{p2} = 6.35381844 \\ h_{p3} = 0 \end{cases}$	$\begin{cases} lu_1 = 0 \\ lu_2 = -0.63396781 \\ lu_3 = -0.31123918 \end{cases}$
次长	$\begin{cases} h_1 = 11.57073920 \\ h_2 = 6.75196959 \\ h_3 = 9.26506292 \end{cases}$	$\begin{cases} h_{p1} = 26.30925755 \\ h_{p2} = 7.03899472 \\ h_{p3} = 0 \end{cases}$	$\begin{cases} lu_1 = 0 \\ lu_2 = -0.56521741 \\ lu_3 = -0.34219843 \end{cases}$
中焦	$\begin{cases} h_1 = 9.33524168 \\ h_2 = 6.15801085 \\ h_3 = 9.41989494 \end{cases}$	$\begin{cases} h_{p1} = 25.75411911 \\ h_{p2} = 8.56771583 \\ h_{p3} = 0 \end{cases}$	$\begin{cases} lu_1 = 0 \\ lu_2 = -0.50000002 \\ lu_3 = -0.35301091 \end{cases}$
次短	$\begin{cases} h_1 = 6.61402881 \\ h_2 = 5.09011703 \\ h_3 = 9.23589913 \end{cases}$	$\begin{cases} h_{p1} = 25.73192083 \\ h_{p2} = 11.75683957 \\ h_{p3} = 0 \end{cases}$	$\begin{cases} lu_1 = 0 \\ lu_2 = -0.42856749 \\ lu_3 = -0.34012169 \end{cases}$
短焦	$\begin{cases} h_1 = 4.46428571 \\ h_2 = 4.02255441 \\ h_3 = 8.84869512 \end{cases}$	$\begin{cases} h_{p1} = 23.76434140 \\ h_{p2} = 16.29347394 \\ h_{p3} = 0 \end{cases}$	$\begin{cases} lu_1 = 0 \\ lu_2 = -0.36604543 \\ lu_3 = -0.31124657 \end{cases}$

⑪ 校正象差的权,一般填写4个1。

⑫  $S_1 \sim S_V$  的目标值,填写20个零(长焦至短焦共有五个焦距位置,每个焦距位置从  $S_1$  至  $S_V$  共有四种象差系数,所

以共有20个目标值)。

⑬  $IP$ 、 $IW$  的权,填写6个零(三个  $IP$  的权,三个  $IW$  的权)。

经过上机计算,平衡后认为满意的一

组数据列于下:

$$|P_3^\infty| = 0.126954, |W_3^\infty| = 0.748264,$$

$$|P_1^\infty| = 0.415346, |W_1^\infty| = 0.105478,$$

$$|P_2^\infty| = 0.316504, |W_2^\infty| = 1.3550007,$$

焦距位置 象差系数	长焦	次长	中焦	次短	短焦
$S_I$	0.061377	0.052059	0.031479	0.006148	-0.007024
$S_{II}$	0.046903	0.042886	0.039678	0.035381	0.032244
$S_{III}$	0.121677	0.141491	0.176057	0.231194	0.286379
$S_V$	0.020404	-0.015098	-0.055529	-0.119069	-0.261443

总的要求是  $|P^\infty|$ 、 $|W^\infty|$  值较小,而且尽量使求得的半径较大。 $S_I \sim S_V$  的各值较小,另则使各象差系数随焦距变化而变动的范围较小。

(7) 分配  $|P|$ 、 $|W|$

计算变倍组:

要求  $|P_2^\infty| = 0.3165$ ,  $|W_2^\infty| = 1.355$ , 我们准备采用如图 4.119 所示的形式。我们取

$$\begin{aligned} \varphi_1 &= 0.6, \varphi_2 = 0.85, \\ \varphi_3 &= -0.45, (\because \varphi_{\text{变倍}} = 1) \end{aligned}$$

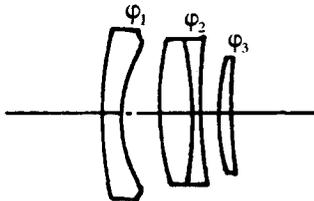


图 4.119

取第 1 块透镜材料为  $LaK_6$ :  $n = 1.69338$ ,  $\nu = 53.4$ , 取第 3 块透镜材料为  $ZF_6$ :  $n = 1.75500$ ,  $\nu = 27.5$ ,

(i) 求单透镜的  $|P_1^\infty|$ 、 $|W_1^\infty|$ 、 $|P_3^\infty|$ 、

$|W_3^\infty|$

第一透镜:

$$\text{取 } r_{1\text{实}} = 180.30, \because r_1 = \frac{1}{c_1},$$

$$r_{1\text{实}} = \frac{f_{\text{变倍}}}{|c_1 \varphi_1|}$$

$$c_1 = \frac{f_{\text{变倍}}}{r_{1\text{实}} \varphi_1} = \frac{-31.6014708}{180.30 \times 0.6}$$

$$= -0.292119$$

$$|Q| = k_2 - 1 = k_1 - \frac{n}{n-1} = -0.292119$$

$$- \frac{1.69338}{1.69338 - 1} = -2.734329,$$

$$|c_2| = |Q| + 1 = -2.734329 + 1$$

$$= -1.734329,$$

$$r_{2\text{实}} = \frac{f_{\text{变倍}}}{|c_2 \varphi_1|} = \frac{-31.6014708}{-1.734329 \times 0.6}$$

$$= 30.369,$$

$$|W_1^\infty| = - \frac{n+1}{n} |Q| - \frac{1}{n-1}$$

$$= - \frac{1.69338 + 1}{1.69338} \times (-2.734329)$$

$$- \frac{1}{1.69338 - 1} = 4.3490457 - 1.4422$$

$$= 2.90685$$

$$|P_{01}| = \frac{n}{(n-1)^2} \left[ 1 - \frac{9}{4(n+2)} \right]$$

$$= \frac{1.69338}{(1.69338 - 1)^2} \left[ 1 - \frac{1}{4(1.69338 + 2)} \right]$$

$$= 3.52218 \times 0.3908 = 1.37647$$

$$|P_1^\infty| = |P_0| + 0.85 [ |W_1^\infty| - 0.15 ]^2$$

$$= 1.37647 + 0.85 [ 2.90685 - 0.15 ]^2$$

$$= 1.37647 + 6.460187 = 7.836657,$$

规范化  $lu$ :

$$lu_2 = \frac{\varphi_1}{\varphi_2} = \frac{0.6}{0.85} = 0.70588$$

$$lu_3 = \frac{\varphi_1 + \varphi_2}{\varphi_3} = \frac{0.6 + 0.85}{-0.45}$$

$$= -3.2222,$$

第三透镜:

$$\text{取 } r_{6\text{实}} = 22.8,$$

$$r_{6\text{实}} = \frac{f_{\text{变倍}}}{lc_6\varphi_3}, lc_6 = \frac{f_{\text{变倍}}}{r_{6\text{实}}\varphi_3}$$

$$= \frac{-31.6014708}{22.8 \times (-0.45)} = 3.080065,$$

$$|Q| = |c_7 - 1| = |c_6 - \frac{n}{n-1}| = 3.080065$$

$$- \frac{1.755}{1.755 - 1} = 0.755565,$$

$$|c_7| = |Q| + 1 = 0.755565 + 1$$

$$= 1.755565,$$

$$r_{7\text{实}} = \frac{f_{\text{变倍}}}{|c_7\varphi_3|} = \frac{-31.6014708}{1.755565 \times (-0.45)}$$

$$= 40,$$

$$|W_3^\infty| = -\frac{n+1}{n}|Q| - \frac{1}{n-1}$$

$$= -\frac{1.755+1}{1.755} \times 0.755565 - \frac{1}{1.755-1}$$

$$= -1.186085 - 1.3245 = -2.5106,$$

$$|W_3| = |W_3^\infty| - (2 + \frac{1}{n})|u_3| = -2.5106$$

$$- (2 - \frac{1}{1.755}) \times (-3.2222) = -2.5106 +$$

$$8.2804 = 5.7698,$$

$$|P_{03}| = \frac{n}{(n-1)^2} [1 - \frac{9}{4(n+2)}]$$

$$= \frac{1.755}{(1.755-1)^2} (1 - \frac{9}{4 \times (1.755+2)})$$

$$= 1.2339,$$

$$|P_{\min}| = |P_{03}| - \frac{n}{n+2} (lu_3 + lu_3^2) = 1.2339$$

$$- \frac{1.755}{1.755+2} [-3.2222 + (-3.2222)^2]$$

$$= 1.2339 - 3.3466 = -2.1127,$$

$$|P_3| = |P_{\min}| + 0.84[|W_3| - 0.14(1 +$$

$$2lu_3)]^2 = -2.1127 + 0.84\{5.7698 - 0.14$$

$$\times [1 + 2 \times (-3.2222)]\}^2 = -2.1127 +$$

$$0.84[5.7698 + 0.14 \times 5.4444]^2$$

$$= -2.1127 + 21.064 = 18.95,$$

(ii) 求  $|P_{02}|$

$$\because |P_{\text{变}}^\infty| = \varphi_1^3 |P_1^\infty| + \varphi_2^3 |P_2^\infty| + \varphi_3^3 |P_3^\infty|$$

$$\therefore |P_2| = \frac{|P_{\text{变}}^\infty| - \varphi_1^3 |P_1^\infty| - \varphi_3^3 |P_3^\infty|}{\varphi_2^3} =$$

$$\frac{0.3165 - 0.6^3 \times 7.837 - (0.45)^3 \times 18.95}{0.85^3}$$

$$= \frac{0.3165 - 1.6928 + 1.7268}{0.614125} = \frac{0.3505}{0.614125}$$

$$= 0.57$$

$$|W_{\text{变}}^\infty| = \varphi_1^2 |W_1^\infty| + \varphi_2^2 |W_2^\infty| + \varphi_3^2 |W_3^\infty|$$

$$|W_2| = \frac{|W_{\text{变}}^\infty| - \varphi_1^2 |W_1^\infty| - \varphi_3^2 |W_3^\infty|}{\varphi_2^2} =$$

$$\frac{1.355 - 0.6^2 \times 2.90685 - 0.45^2 \times 5.7698}{0.85^2}$$

$$= \frac{1.355 - 1.046 - 1.168}{0.7225} = -1.1889,$$

$$|W_2^\infty| = |W_2| - |u_2|(2 + \mu) = -1.1889 -$$

$$0.70588(2 + 0.6) = -3.0242,$$

$$|P_2^\infty| = |P_2| - |u_2|(4|W_2^\infty| - 1) - |u_2|^2(3 +$$

$$2\mu) = 0.57 - 0.70588[4(-3.0242) - 1]$$

$$- 0.70588^2 \times (3 + 2 \times 0.6) = 0.57 +$$

$$9.245 - 2.093 = 7.722,$$

$$|P_{02}| = |P_2^\infty| - 0.84(|W_2^\infty| - 0.14)^2 =$$

$$7.722 - 0.84(-3.0242 - 0.14)^2 = 7.722$$

$$- 8.41 = -0.688。$$

(iii) 求色差系数  $lc_2$

$$lc_2 = - \left( \frac{\varphi_1}{\nu_1} + \frac{\varphi_3}{\nu_3} \right) \frac{1}{\varphi_2} = - \left( \frac{0.6}{53.4} + \frac{-0.45}{27.5} \right) \frac{1}{0.85} = (0.011235 - 0.01636) \times \frac{1}{0.85} = 0.00603,$$

故要求双胶为: 
$$\begin{cases} lP_{02} = -0.688 \\ lc_2 = 0.00603 \end{cases}$$

根据  $lP_{02}$ 、 $lc_2$  进行选玻璃, 接下来是求双胶透镜的曲率半径等, 这里不一一计算了。关于其它两透镜组的  $lP$ 、 $lW$  分配及下面几步计算这里不作叙述了。

3. 例 3. 设计一个三组元光学补偿系统, 要求  $f'40 \sim 80$ , 正组在前, 正正连动 (如图 4.120 所示)。

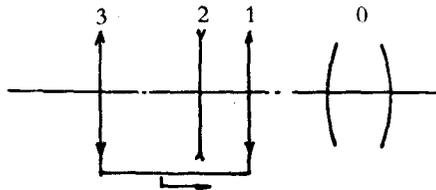


图 4.120

本例只分配焦距和间隔, 达到要求的象面位移。

计算步骤如下:

1) 变倍比:

$$R = \frac{F_{\max}}{F_{\min}} = \frac{80}{40} = 2,$$

$$2) \tau = \frac{R-1}{R+1} = \frac{2-1}{2+1} = \frac{1}{3},$$

$$3) \theta = 0.0218\tau^4 [(1 - 1.463\tau^2 + 0.722\tau^4) - 0.171\tau(1 - 1.51\tau^2 + 0.67\tau^4)] \\ = 0.0218 \times \left(\frac{1}{3}\right)^4 [(1 - 1.463 \times \left(\frac{1}{3}\right)^2 + 0.722 \left(\frac{1}{3}\right)^4) - 0.171 \times \frac{1}{3} (1 - 1.51 \times$$

$$\left(\frac{1}{3}\right)^2 + 0.67 \times \left(\frac{1}{3}\right)^4] = 0.000212575.$$

$$4) y = \theta \frac{F_{\max}^2}{zm} = 0.000212575 \times \frac{80^2}{25} = 0.0544,$$

(这里取  $zm = 25$ , 即为最大导程,  $y$  为最大象面位移)

$$5) l'_i(0) = \frac{1.703}{\tau} [(1 - 0.294\tau^2 - 0.171\tau^4) + 0.44\tau(1 - 0.05\tau^2 - 0.01\tau^4)] \\ = \frac{1.703}{\frac{1}{3}} [(1 - 0.294 \times \left(\frac{1}{3}\right)^2 - 0.171 \times \left(\frac{1}{3}\right)^4) + 0.44 \times \frac{1}{3} (1 - 0.05 \times \left(\frac{1}{3}\right)^2 - 0.01 \times \left(\frac{1}{3}\right)^4)] = 5.676$$

$$6) \epsilon = 0.1508\tau(1 + 0.17\tau^2 + 0.15\tau^4) = 0.1508 \times \frac{1}{3} [1 + 0.17 \times \left(\frac{1}{3}\right)^2 + 0.15 \times \left(\frac{1}{3}\right)^4] = 0.0513 \text{ (补偿点偏移量)},$$

7) 取  $z_1 = 0$

$$z_2 = 0.5 - \epsilon = 0.5 - 0.0513 = 0.4487,$$

$z_3 = 1,$

$$8) r_1 = z_1 + z_2 + z_3 = z_2 + 1 = 1.4487,$$

$$r_2 = z_1z_2 + z_2z_3 + z_1z_3 = z_2 = 0.4487,$$

$r_3 = z_1z_2z_3 = 0$

$$9) m = \frac{1}{4} \left( \frac{1}{\tau} + 2\epsilon \right) = \frac{1}{4} (3 + 2 \times 0.0513) = \frac{3.1026}{4} = 0.77565,$$

$$10) \lambda = [l - 0.5 - |(m - \epsilon)|]$$

$$= 5.676 - 0.5 - |(0.77565 - 0.0513)|$$

$$= 5.176 - 0.72435 = 4.45165,$$

$$11) f_1 = (\lambda^2 - m^2)/2\lambda = (4.45165^2 - 0.77565^2)/(2 \times 4.45165) = \frac{19.215556}{8.9033}$$

$$= 2.15825099,$$

$$12) X' = l - f_1 = 5.676 - 2.15825099 = 3.51774901,$$

$$13) \beta_2 = X' - (\frac{1}{2} - \epsilon) = 3.51774901 - (0.5 - 0.0513) = 3.06904901,$$

$$14) b_1 = \beta_2 - 1 = 3.06904901 - 1 = 2.06904901,$$

$$15) b_2 = \beta_2/(r - 1) = \frac{3.06904901}{2 - 1} = 3.06904901, (\because r = R),$$

$$16) a_1 = b_2 X'/f_1^2 = \frac{3.06904901 \times 3.51774901}{2.15825099^2}$$

$$= 2.31774032,$$

$$17) d_{23} = -a = -2.31774032,$$

$$18) d_{21} = d_{23} + b_1 = -2.31774032 + 2.06904901 = -0.24869131,$$

$$19) f_2 = -\sqrt{d_{23}d_{21} + b_2}$$

$$= -\sqrt{(-2.31774032) \times (-0.24869131)} + 3.06904901 = -\sqrt{0.57640188 + 3.06904901}$$

$$= -1.9093064,$$

$$20) S_{21} = f_1 + d_{21} - |f_2| = 2.15825099 - 0.24869131 - 1.9093064$$

$$= 0.00025328 \text{ (即为第2组与第1组的主面间隔, 认为太小.)}$$

重新取  $l = 5.8$ , 从 10) 式开始计算:

$$10) \lambda = [l - 0.5 - |m - \epsilon|]$$

$$= [5.8 - 0.5 - |(0.77565 - 0.0513)|]$$

$$= 4.57565,$$

$$11) f_1 = (\lambda^2 - m^2)/2\lambda$$

$$= \frac{4.57565^2 - 0.77565^2}{2 \times 4.57565} = 2.22208221,$$

$$12) X' = l - f_1 = 5.8 - 2.22208221 = 3.57791729,$$

$$13) \beta_2 = X' - (\frac{1}{2} - \epsilon) = 3.57791729 - (0.5 - 0.0513) = 3.12921779,$$

$$14) b_1 = \beta_2 - 1 = 2.12921779,$$

$$15) b_2 = \beta_2/(r - 1) = \frac{3.12921779}{2 - 1} = 3.12921779,$$

$$16) a_1 = b_2 X'/f_1^2 = (3.12921779 \times 3.57791729)/2.22208221^2$$

$$= 2.26749273,$$

$$17) d_{23} = -a_1 = -2.26749273,$$

$$18) d_{21} = d_{23} + b_1 = -2.26749273 + 2.12921779 = -0.13827494,$$

$$19) f_2 = -\sqrt{d_{23}d_{21} + b_2}$$

$$= -\sqrt{(-2.26749273) \times (-0.13827494)} + 3.12921779 = -\sqrt{3.44275521}$$

$$= -1.85546631,$$

$$20) S_{21} = f_1 + d_{21} - |f_2| = 2.22208221 + (-0.13827494) - 1.85546631 = 0.22834096 \text{ (此数可以。主要是考虑第2组元与第1组元实际不碰.)}$$

$$21) \text{取 } S_{32} = 1.15 \text{ (} S_{32} \text{为第3组元与第2组元在长焦时的主面间隔, 要大于1.)}$$

$$22) f_3 = |f_2| - d_{32} + S_{32} = 1.85546631 - (-2.26749273) + 1.15 = 5.27295904,$$

$$23) f_{\max} = -\left(\frac{2\tau}{1 - |\tau|}\right) \frac{f_1 f_2 f_3}{\beta_2}$$

$$= -\left(\frac{2/3}{1 - \frac{1}{3}}\right) \times \frac{2.22208221 \times (-1.85546631) \times 5.27295904}{3.12921779}$$

$$= \frac{21.74040316}{3.12921779} = 6.94755195,$$

24)  $L'_{(0)} = l_{zm} = 5.8 \times 25 = 145$  (变倍组象距),

$$25) W = \frac{f_{\max} \cdot zm}{F_{\max}}$$

$$= \frac{6.94755195 \times 25}{80} = 2.17110999,$$

26) 取  $S_{10} = 25 \times 1.3 = 32.5$ ,

27)  $L_0 = L'_{(0)} - S_{10} = 145 - 32.5 = 112.5$ ,

28)  $L'_0 = \frac{L_0}{W} = \frac{112.5}{2.17110999} = 51.81681283$ ,

29)  $F_0 = \frac{L_0}{W - 1} = \frac{112.5}{1.17110999} = 96.06271055$ ,

小结:

$$L'_0 = 51.81681283,$$

$$F_0 = 96.06271055,$$

$$S_{10} = 32.5$$

$$F_1 = 2.22208221 \times 25 = 55.55205525$$

$$S_{21} = 5.708524,$$

$$F_2 = -1.85546631 \times 25 = -46.38665775$$

$$S_{32} = 28.75$$

$$F_3 = 5.27295904 \times 25 = 131.823975$$

总长 = 118.77534.  
(未完待续)



## 可自动对焦的液体“露珠”镜头

透过一滴露珠,可以看清整个世界,人们在日常生活中往往忽视的细节被法国科学家捕捉到,开发出了不用机械部件就可以对焦的液体“露珠”镜头。

据法国媒体报道,2月13日在西班牙巴塞罗那召开的3G世界年会上,法国 Varioptic 公司发明的可自动对焦的液体“露珠”镜头引起人们极大好奇。这种镜头的主要材料是油和水。露珠的伸缩弹性不同,所折射的景象就不同,这与机械镜头伸缩对焦是一个道理。利用这一特点,他们开发了世界首款用于手机的液体“露珠”镜头。

科学家介绍说,液体镜头是将水溶液和油密封在金属筒中,通过控制两种液体交界面的曲面半径调节焦距。当需要聚焦和变焦时,电子程序只需改变两极电压来修改两滴液体的外形,就可达到目的。与传统镜头相比,这种镜头体积很小、价格低、耗电量小、变焦速度只有0.02s、成像质量好。目前,全球许多手机生产厂商都已经准备广泛采用这种液体“露珠”镜头,推出可自动对焦拍照的手机。

一些专业媒体认为,法国科学家的这个奇想,有望改变光学领域的研究方向。液体“露珠”镜头由于省却了机械镜头大量的机械动作,可以大大延长使用寿命。此外,由于体积非常小,有望在未来取代相机、内窥镜、光网络设备、遥测设备、军用光学设备以及其他市场中的小型玻璃和塑料镜头。

摘自《科技日报》